Supplementary Materiels: DSDNet

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1 Overview

We present additional results in this supplementary document. First, we show the detailed network configurations in Section 2. Second, we provide further detailed analysis on the effect of the proposed critical components in our method (Section 3). Then we show more qualitative comparisons of the state-of-the-art methods and our models (Section 4). Finally, Section 5 shows some failure cases and analyzes the limitations of the proposed method.

2 Detailed Network Configurations

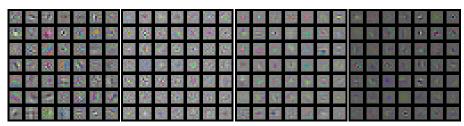
We show the detailed network configurations in Table 1.

Table 1: Architecture of the proposed DSDNet. "conv", "tconv", "Max-Pool" and "Avg-Pool" denote the convolutional layer, transposed convolutional layer, Max Pooling layer and Average Pooling layer, respectively. We describe the parameters of these layers. We use 1×1 kernels in "HypNet" as the bottleneck of the Inception Net [12].

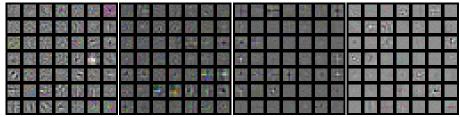
	1	\mathcal{N}_F	\mathcal{N}_G	Maxout	CGNet	NLNet	HypNet
		JVF	JVG	Maxout	Carvet	1111160	TTyprice
conv	kernel	7×7	7×7	3×3	3×3	3×3	3×3
							1×1
tconv	kernel				3×3		
	stride				2×2		
Max-Pool	kernel			$4 \times 1 \times 1$	3×3		
	stride			$4\times1\times1$	2×2		
Avg-Pool	kernel					3×3	
ReLU					✓	✓	✓
SoftPlus	β					1	
	threshold					20	
Sigmoid							✓

3 More Ablation Studies

We show some intermediate results in Fig. 1, 2 and 3 based on the full-weighted model to better understand what the proposed network learns. In Fig. 1, we show the learned **F** and **G**. We use the BABY image from SET5 [1] as an example and



(a) **F** of the first stage (b) **F** of the second stage(c) **F** of the third stage (d) **F** of the latest stage



(e) ${f G}$ of the first stage (f) ${f G}$ of the second stage(g) ${f G}$ of the third stage (h) ${f G}$ of the latest stage

Fig. 1: Learned filters of \mathcal{N}_F and \mathcal{N}_G .

compute the feature maps. Fig. 2 and Fig. 3 show the regularization-related and data-related feature maps, respectively.

In Table 2, we show the complete ablation study in PSNR and SSIM on the datasets Levin [6], BSD100 [7] and Set5 [1] based on the heavy-weighted model consistently with Section 5.5 of the manuscript. The manuscript states that we include the ablation studies w.r.t. HypNet and NLNet in the supplemental material. In addition, we replace the Maxout layers with soft-shrinkage functions (e.g., ℓ_1 -norm in Table 2 and Figure 4) and compare them to cascade shrinkage fields (CSF) [11] to demonstrate the effectiveness of Maxout layers against conventional shrinkage functions.

Fig. 4 shows the visual comparisons of the baseline methods, where this work generates a clearer image that is visually close to the ground truth.

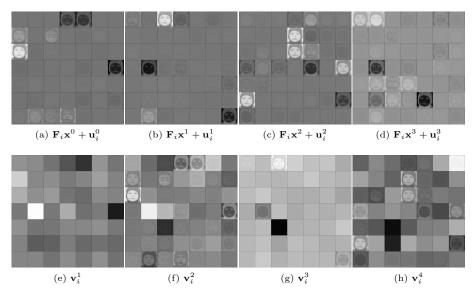


Fig. 2: The regularization-related feature maps before (top row) and after (bottom row) the Maxout layers. As regularization-related terms are learned to keep the structure of images, we can observe the strong edges in the figure. The Maxout layers enhance the edges.

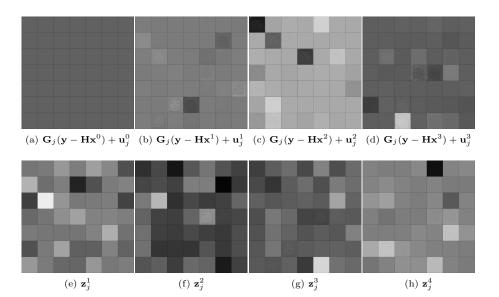


Fig. 3: Data-related feature maps before (top row) and after (bottom row) the Maxout layers. As data-related terms are learned to eliminate the reconstruction error and noise, we can observe the sparsity in the figure. The Maxout layers enhance the sparsity.

Table 2: Average PSNR(dB)/SSIM of the deblurring results with Gaussian noise using different methods. We highlight the **best** results. "CSF" denotes the result of [11], "w/o **F**, **G**", "ReLU", "RBF", "CG", "CG[†]", "FFT" and "FFT[†]" are the extended results of Table 5 of the manuscript; "w/o HypNet" and "w/o NLNet" are results of the models without these parts, respectively; " ℓ_1 -norm" replaces the Maxout layers with soft-shrinkage functions, i.e., the R_i 's and R_j 's in Equation (8) of the manuscript are all in the form of ℓ_1 -norm regularization.

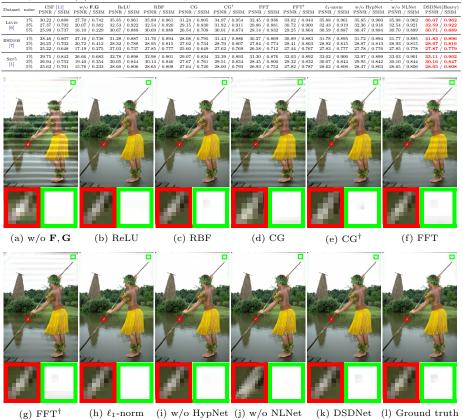


Fig. 4: Qualitative ablation study on the BSD100 dataset [7] with 1% Gaussian noise. We note that the method without using the learned filters generates significant artifacts, as shown in (a). The method using RBFs generates oversmoothed results, as shown in (c). The ReLU does not discriminatively keep the most valuable features, so it does not restore the details well (see (b)). The results of original CG in (d) and (f) still contain ringing artifacts. As mentioned in the manuscript, FFT-based methods (f) and (g) generate ring artifacts even with edge taper, where (g) is more severe than (e). The models without HypNet and NLNet do not effectively restore the patterns as shown in the green boxes in (i) and (j). (h) shows the result of soft-shrinkage functions which do not preserve details well. (b), (c) and (h) demonstrate the effectiveness of Maxout layers. The proposed method (k) generates a better result that is visually close to the ground truth.

4 More Qualitative Evaluation

In this section, we present more visual comparisons of the proposed method and state-of-the-art ones.

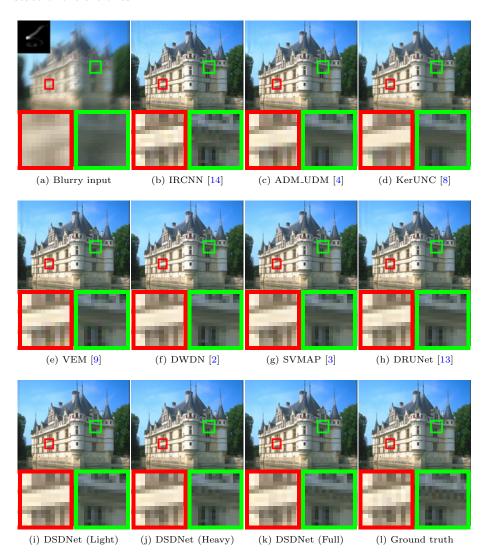


Fig. 5: Qualitative evaluation of 1% Gaussian noise on BSD100 [7]. The result by the IRCNN [14] contains some artifacts. The other evaluated methods do not effectively restore the structural details. In contrast, our methods generate clearer images.



Fig. 6: Qualitative evaluation of 1% Gaussian noise on BSD100 [7]. Our models generate sharper texture both in the red and green boxes than other methods.

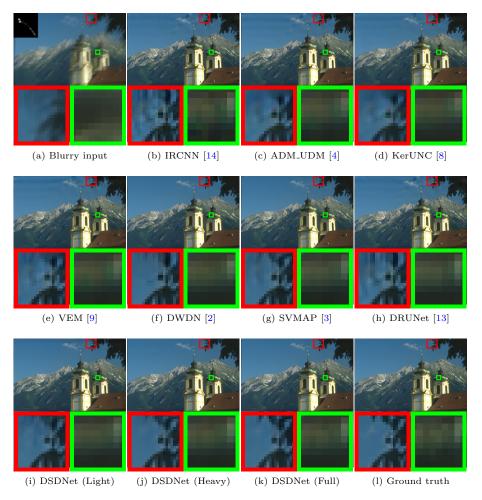


Fig. 7: Qualitative evaluation of 1% Gaussian noise on BSD100 [7]. Only the red boxes of our (j) and (k) are out of artifacts. Besides, only the green boxes of these two models keep the sharp details.



Fig. 8: Qualitative evaluation of 3% Gaussian noise on BSD100 [7]. The contents in (k) are clearer than other methods.

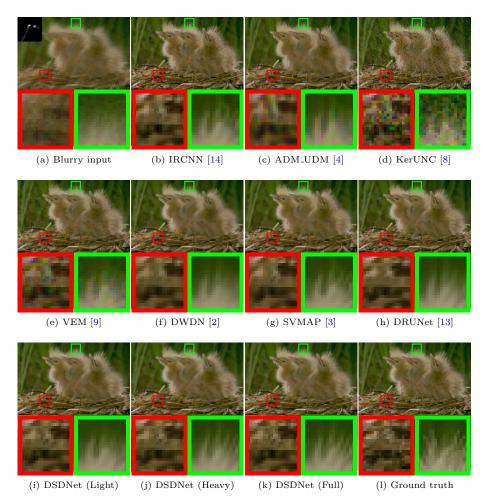


Fig. 9: Qualitative evaluation of 5% Gaussian noise on BSD100 [7]. The texture in (j) and (k) are sharper than other methods, while that of our light-weighted model (i) is very close to state-of-the-art methods (g) and (h).

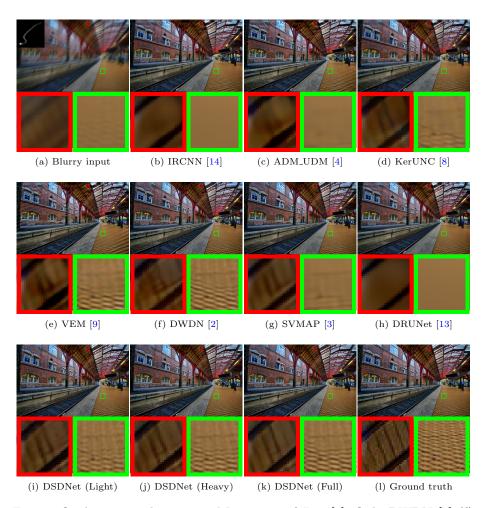


Fig. 10: Qualitative evaluation on Manmade of Lai [5]. Only DWDN [2] (f) and our methods reconstruct the texture in green boxes, while the red box of (f) contains artifacts as other methods.

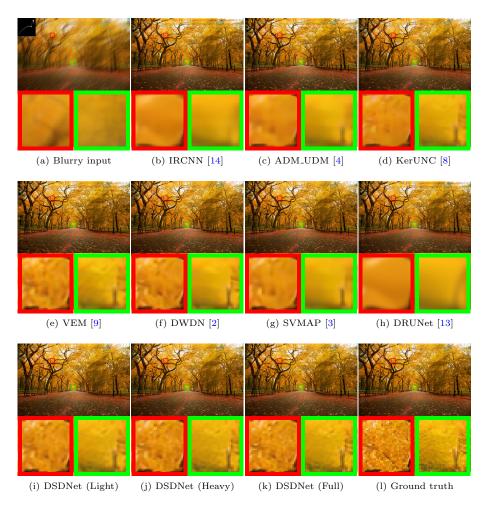


Fig. 11: Qualitative evaluation on Natural of Lai [5]. The evaluated methods do not restore the details well, as shown in (b)-(h). In contrast, our method restores much clearer images with finer details.

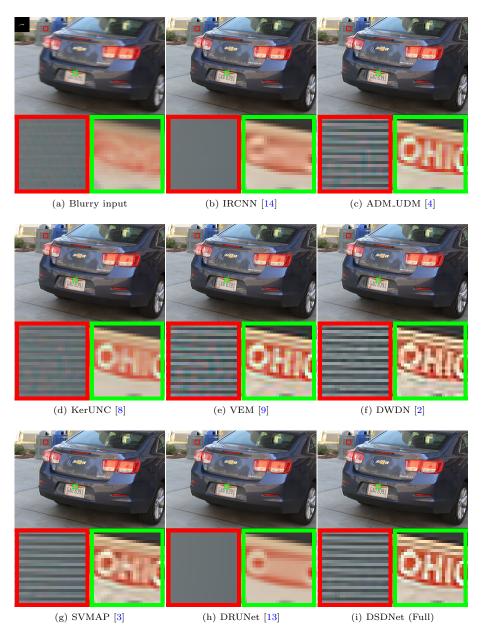


Fig. 12: Qualitative evaluation on a real case uses the kernel estimated by [10]. The evaluated methods do not restore the details well, as shown in (b)-(h). In contrast, our method restore much clearer images with finer details.

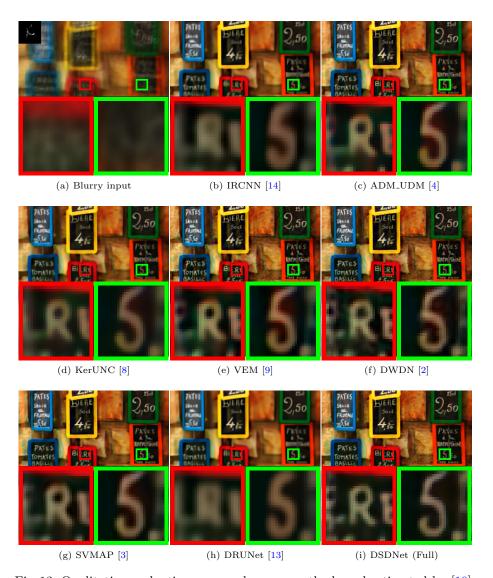


Fig. 13: Qualitative evaluation on a real case uses the kernel estimated by [10]. The evaluated methods mix the white texts with surrounding colors in (b) - (h). In contrast, our method restores much sharper texts with less mixed color.

5 Limitation

In Section 5.6 of the manuscript, we have pointed out that our method is less effective when the blurry images contain significant saturation. Because the linear convolution model used in the degradation process does not hold for saturation, methods based on such a degradation model will generate the results with significant artifacts, as shown in Fig. 14(b).

As the pixels in the saturated regions usually have higher intensity values, clipping these pixels and ignoring them in the deblurring process would help the performance improvement (Fig. 14(c)). Since deblurring images with saturated regions is an important task, future work will consider jointly handling saturated areas and image deblurring in a principled way.



Fig. 14: A failure example. Images containing dark and saturated pixels may cause overflow, as shown in (b). Clipping these pixels and ignoring them in the deblurring process generates a good result, as shown in (c).

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